

MP350 Classical Mechanics

Lagrangian mechanics — summary sheet

1. **Lagrangian** $L = T - V =$ kinetic energy – potential energy.

$L = L(q, \dot{q}, t)$ is a function of the coordinates q_i , their time derivatives \dot{q}_i and time t .

2. **Generalised coordinates**

For a system of N particles, we may instead of cartesian coordinates $\vec{r}_i = (x_i, y_i, z_i)$, $i = 1 \dots N$, use *any* set of coordinates

$$q_j = f_j(\vec{r}_1, \dots, \vec{r}_N), \quad j = 1 \dots M.$$

M is the *number of degrees of freedom* of the system. For an unconstrained system $M = 3N$, but if there are constraints then $M < 3N$.

3. **Principle of least action**

Nature “chooses” the path $q(t)$ that minimises the action

$$S = \int_{t_0}^{t_1} L(q(t), \dot{q}(t), t) dt$$

with $q(t_0) = q_0, q(t_1) = q_1$ kept fixed, or

$$\delta S = \lim_{\alpha \rightarrow 0} \frac{S[q(t)] - S[q(t) + \alpha h(t)]}{\alpha} = 0$$

for *arbitrary* $h(t)$ with $h(t_0) = h(t_1) = 0$. This leads to

4. **Euler–Lagrange equations**

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} - \frac{\partial L}{\partial q_i} = 0$$

5. Canonical momentum

$$p_i = \frac{\partial L}{\partial \dot{q}_i}$$

(a) *Linear momentum*

If $q_i = x_i$ and $L = \frac{1}{2} \sum_i m_i \dot{x}_i^2 - V(x)$, then $p_i = m \dot{x}_i$.

(b) *Angular momentum*

If q_i is a rotational angle ϕ about some axis, then p_i is the angular momentum [$\vec{L} = \vec{r} \times (m \vec{v})$] about that axis.

6. Conservation laws

From the Euler–Lagrange equations we see that if L does not depend explicitly on the coordinate q_i then

$$\frac{dp_i}{dt} = 0 \quad \iff \quad p_i \text{ is conserved.}$$

7. Hamiltonian

$$H = \sum_i p_i \dot{q}_i - L$$

If there are no time-dependent constraints or velocity-dependent forces (or potentials) then $H = T + V =$ total energy.

$$\frac{dH}{dt} = -\frac{\partial L}{\partial t},$$

so if the lagrangian L does not explicitly depend on time, then the hamiltonian H is conserved.