

* Remember similar derivation of $\vec{\nabla} \cdot \vec{E} = \rho$
 from Gauss's flux theorem, using Gauss's
 divergence theorem.

* Magnetostatics
 in differential form

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \quad \left[\text{will be corrected} \right]$$

Electrostatics in
 differential form

$$\vec{\nabla} \cdot \vec{E} = \rho / \epsilon_0$$

$$\vec{\nabla} \times \vec{E} = 0 \quad \left[\text{will be corrected} \right]$$

corrected forms will be Maxwell-III
 & Maxwell-IV

	Charges & steady currents	Fields acts on charge	How fields are created	Integral theorems
Electrostatics	$Q = \int \rho dV = \int \rho d^3r$ $Q = \int \sigma dS = \int \sigma da$ $Q = \int \rho_{add}$	$\vec{F} = q\vec{E}$	$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{(\vec{r}-\vec{r}')}{ \vec{r}-\vec{r}' ^2}$ + superposition principle $d\vec{B} = \frac{\mu_0 I}{4\pi} \frac{d\vec{r}' \times (\vec{r}-\vec{r}')}{ \vec{r}-\vec{r}' ^2}$ + superposition principle	GAUSS'S theorem (Divergence = flux thru m) $\oint \vec{E} \cdot d\vec{S} = \frac{1}{\epsilon_0} Q_{enc.}$
Magneto-statics	$I = \int \vec{J} \cdot d\vec{S}$	$\vec{F} = q\vec{v} \times \vec{B}$ $d\vec{F} = I d\vec{l} \times \vec{B}$	Ampere's theorem $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc.}$	Ampere's theorem
Electrostatics	D.I.V. $\vec{\nabla} \cdot \vec{E} = \rho / \epsilon_0$ GAUSS'p	CURL $\vec{\nabla} \times \vec{E} = 0$	<u>Potential</u> $\vec{E} = -\vec{\nabla} V$ (possible because $\vec{\nabla} \times \vec{E} = 0$ ⇒ still need correction)	$V = - \int_{r_0}^{r^n} \vec{E} \cdot d\vec{r}$ Depends on r_0 !
Magneto-statics	$\vec{\nabla} \cdot \vec{B} = 0$	$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$ (AMPERE)	$\vec{B} = \vec{\nabla} \times \vec{A}$ possible because $\vec{\nabla} \cdot \vec{B} = 0$ $V =$ electric potential / scalar potential $\vec{A} =$ vector potential	\vec{A} depends on "gauge" choice

REVIEW

will need time-dependent current

(12)

* We also learned: $\vec{E} = \sigma \vec{J}$, $\vec{J} = \rho \vec{E}$, $V = RI$
 where σ , ρ , R are material- & temperature-dependent.

* We learned the CONTINUITY EQUATION

$$\vec{\nabla} \cdot \vec{J} + \frac{\partial \rho}{\partial t} = 0$$

For steady current: $\frac{\partial \rho}{\partial t} = 0$, $\vec{\nabla} \cdot \vec{J} = 0$

* Is Ampere's law ($\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$) consistent with the continuity equation?

Since $\vec{J} = \frac{1}{\mu_0} \vec{\nabla} \times \vec{B}$,

$$\vec{\nabla} \cdot \vec{J} = \frac{1}{\mu_0} \vec{\nabla} \cdot (\vec{\nabla} \times \vec{B}) = 0$$

\Rightarrow consistent, only for steady currents, $\rho = \text{const.}$

When $\frac{\partial \rho}{\partial t} \neq 0$,

not consistent! $\rightarrow \vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$ has to be corrected

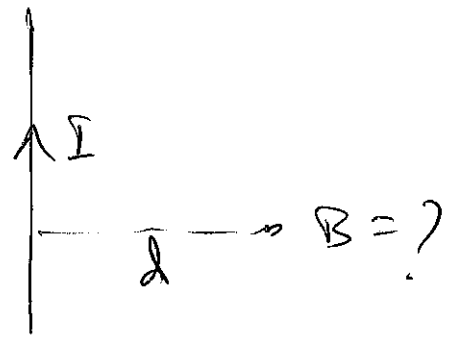
For consistency, one needs $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

Because then $\vec{J} = \frac{1}{\mu_0} \vec{\nabla} \times \vec{B} - \epsilon_0 \frac{\partial \vec{E}}{\partial t}$

so that $\vec{\nabla} \cdot \vec{J} = 0 - \epsilon_0 \frac{\partial}{\partial t} (\vec{\nabla} \cdot \vec{E}) = -\epsilon_0 \frac{\partial}{\partial t} \frac{\rho}{\epsilon_0} = -\frac{\partial \rho}{\partial t}$

Using Ampere's law/theorem

Example 1a Long thin wire



Top view

(We know already)

$$B = \frac{\mu_0 I}{2\pi d}$$



← Amperean loop/curve

By symmetry, \vec{B} points along curve and is the same at all points on curve

$$\oint \vec{B} \cdot d\vec{l}$$

$$= \oint B dl = B \oint dl = B \cdot 2\pi d$$

Ampere's law gives $B \cdot 2\pi d = \mu_0 I$

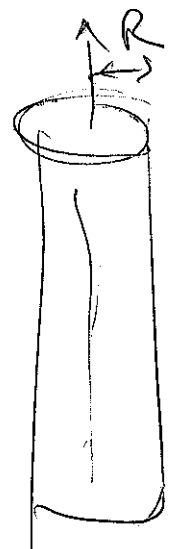
$$\Rightarrow B = \frac{\mu_0 I}{2\pi d}$$

Example 1b

Long thick wire, cylindrically symmetric current density



J depends only on r

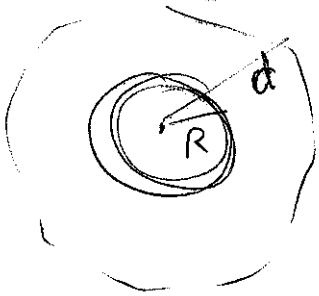


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$$I = \int \vec{J} \cdot d\vec{S} = 2\pi \int_0^R r J(r) dr$$

$(dS = 2\pi r dr)$

Outside wire ($d > R$)

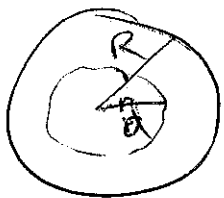


$$B \cdot 2\pi d = \mu_0 I$$

$$B(d) = \frac{\mu_0 I}{2\pi d}$$

Exactly as
for thin wire

Inside wire ($d < R$)



$$B \cdot 2\pi d = \mu_0 I_{enc.}$$

$$= \mu_0 \cdot 2\pi \int_0^d r J(r) dr$$

$$B = \frac{\mu_0}{d} \int_0^d r J(r) dr$$

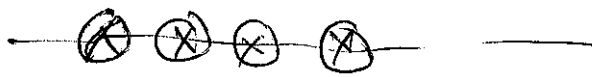
If $J(r) = \text{constant}$, then $J = \frac{I}{\pi R^2}$

$$\text{then } B(d) = \frac{\mu_0}{d} \cdot \frac{I}{\pi R^2} \cdot \frac{d^2}{2} = \frac{\mu_0 I}{2\pi} \frac{d}{R^2}$$

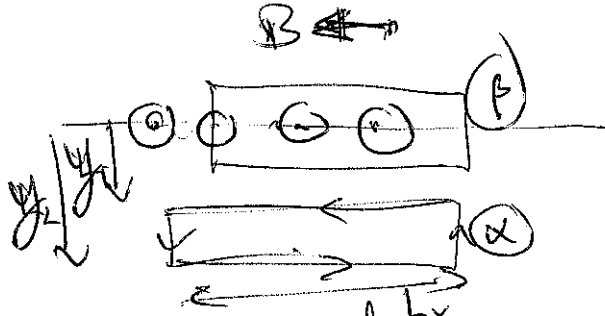
Exercise! Show that inside & outside formulae match at $d = R$.

Infinitely long solenoid

We found, ~~on~~ on axis only, using B-S law,



$$B = \mu_0 n I$$



$n =$ turns per unit length

Using symmetry arguments, \vec{B} must point parallel to axis everywhere, leftward inside, rightward outside.

Consider loop outside (X): $\oint \vec{B} \cdot d\vec{l} = B(y_1)L_x - B(y_2)L_x$

$$\Rightarrow B(y_1) = B(y_2) = B(\infty) = 0$$

\Rightarrow Field outside is ZERO!

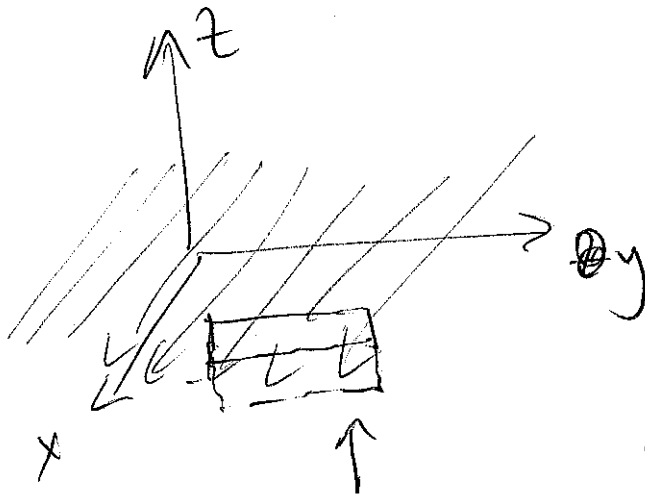
Consider loop, ~~inside~~ ^{straddling the coil surface} (P):

$$B \cdot L_x = \mu_0 n I$$

$$\Rightarrow B = \mu_0 n I \quad \text{EVERYWHERE INSIDE SOLENOID!}$$

\Rightarrow Solenoid can be used to produce ^{nearly} uniform field.

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* Infinite surface of currentoptional

Can prove using
such Amperian loop

$$B \cdot L_y + B \cdot L_y = \mu_0 K L_y$$

$$\Rightarrow B = \frac{\mu_0}{2} K$$

$$\vec{B} = \frac{\mu_0}{2} K \hat{j} \quad z < 0$$

$$- \frac{\mu_0}{2} K \hat{j} \quad \text{for } z > 0$$

Surface current not
so strange. Simply
think of many parallel
wires packed next
to each other. If
 n wires per unit
length, $K = nI$

The Magnetic Vector Potential

$\nabla \times \vec{E} = 0$ allows us to write $\vec{E} = -\nabla V$ in electrostatics.

V is defined upto a constant.

$\nabla \cdot \vec{B} = 0$ allows us to write $\vec{B} = \nabla \times \vec{A}$

If a vector with zero curl is added to ~~the~~ \vec{A} , that vector potential will give the same \vec{B} -field. \Rightarrow ~~the~~ Large freedom in choice of \vec{A} . ~~the~~ Often called "gauge" freedom.

$\vec{A} \rightarrow \vec{A} + \nabla f$ is a "gauge" transform.

Notice $\nabla \times \vec{A} = \nabla \times (\vec{A} + \nabla f)$ b/c $\nabla \times \nabla f = 0$

A common choice: impose $\boxed{\nabla \cdot \vec{A} = 0}$
Coulomb condition / gauge

\Rightarrow even with this condition, many choices of \vec{A} will produce same \vec{B} -field.

48 \vec{E} and \vec{B} fields are "physical" (measurable).
 V and \vec{A} potentials are mathematical constructs.
 (Not measurable but very important.)

* With the Coulomb condition, $(\vec{\nabla} \cdot \vec{A} = 0)$, we get
 $\vec{\nabla} \times \vec{B} = \vec{\nabla} \times (\vec{\nabla} \times \vec{A}) = \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \nabla^2 \vec{A} = -\nabla^2 \vec{A}$

So Ampere's law becomes

$$\boxed{\nabla^2 \vec{A} = -\mu_0 \vec{J}}$$

Ampere's law with Coulomb condition.

* Calculating electric and magnetic potentials.

Electric potentials are determined by

$$\boxed{\nabla^2 V = -\frac{\rho}{\epsilon_0}}$$

Poisson's Equation.

Obtained by combining
 $\vec{E} = -\vec{\nabla} V$ and $\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$

and $\vec{\nabla} \cdot (\vec{\nabla} f) = \nabla^2 f$

In free space ($\rho=0$),

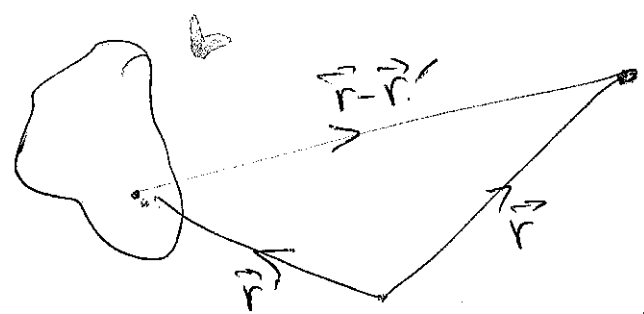
$$\boxed{\nabla^2 V = 0}$$

Laplace's Equation.

* Solving Poisson's equation [obtaining $V(\vec{r})$ for a given $\rho(\vec{r})$] is a rich topic — many methods exist. General solution:

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \sum_{i=1}^n \frac{q_i(\vec{r}_i)}{|\vec{r} - \vec{r}_i|} \quad \text{for point charges}$$

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{|\vec{r} - \vec{r}'|} d^3\vec{r}'$$



Many approximations and tricks exist. [MULTIPOLE EXPANSION, METHOD OF IMAGES, ...]

* Ampere's law with Coulomb condition:

$$\nabla^2 \vec{A} = -\mu_0 \vec{J}$$

Each Cartesian component is a Poisson's equation:

$$\nabla^2 A_x = -\mu_0 J_x, \quad \nabla^2 A_y = -\mu_0 J_y, \quad \nabla^2 A_z = -\mu_0 J_z$$

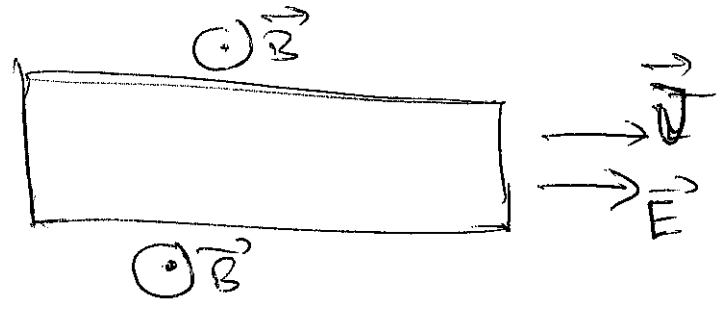
$$\Rightarrow \vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{\vec{J}(\vec{r}')}{|\vec{r} - \vec{r}'|} d^3\vec{r}' \quad \text{Same methods can be used.}$$

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The HALL effect

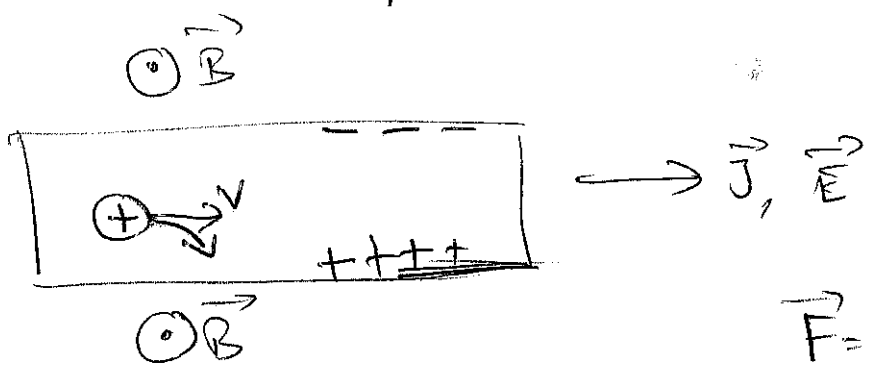
optional

Consider conducting slab, in perpend. magnetic field:



The CARRIERS are then pushed in third perpendicular direction. (Lorentz force law).

If CARRIERS are positive :



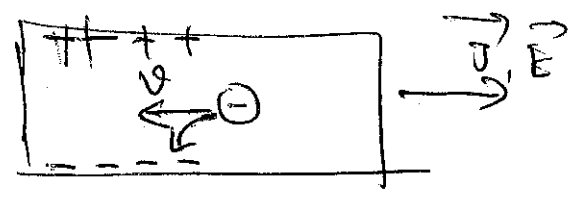
$$\vec{F} = q\vec{v} \times \vec{B}$$

Charges accumulate at edge

⇒ additional \vec{E} -field (voltage) created in transverse direction.

If CARRIERS ARE negative :

$$\vec{F} = (-e)\vec{v} \times \vec{B}$$





Negative carriers deflected in the same direction.

(b1)

⇒ Transverse voltage / \vec{E} -field created in opposite direction.

⇒ Hall experiment can identify sign of carriers. (negative for most but not all materials)

* ELECTROMAGNETIC INDUCTION, FARADAY'S LAW

* Electromotive force (EMF):

- not a force, more like a voltage or potential difference.
- In static or steady-state situations, the potential difference (voltage) drives a current through a wire or loop/circuit.
- EMF is the generalization, for static + dynamic situations.

$$\Sigma = \oint \vec{f} \cdot d\vec{l}$$

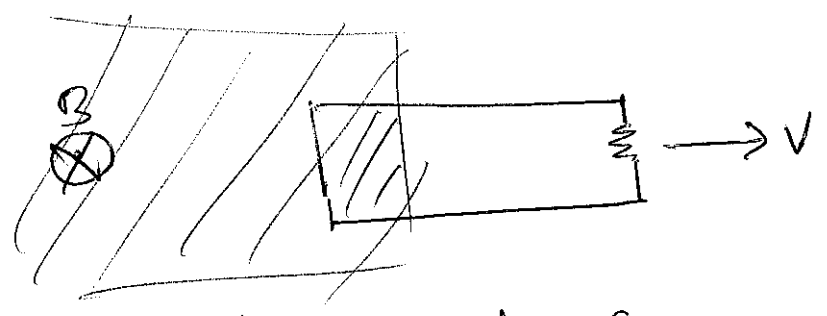
EMF around a circuit.

where \vec{f} is the force per unit charge driving the current = Electric field.

* Motional EMF

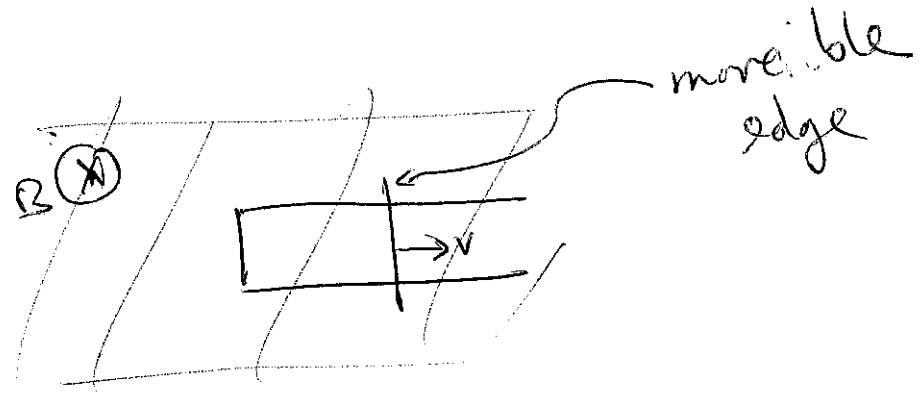
If the magnetic flux through a circuit changes, an EMF is created in the circuit.

Ex. 1



Flux decreases, magnetic force causes charges to move, drives current. (EMF created)

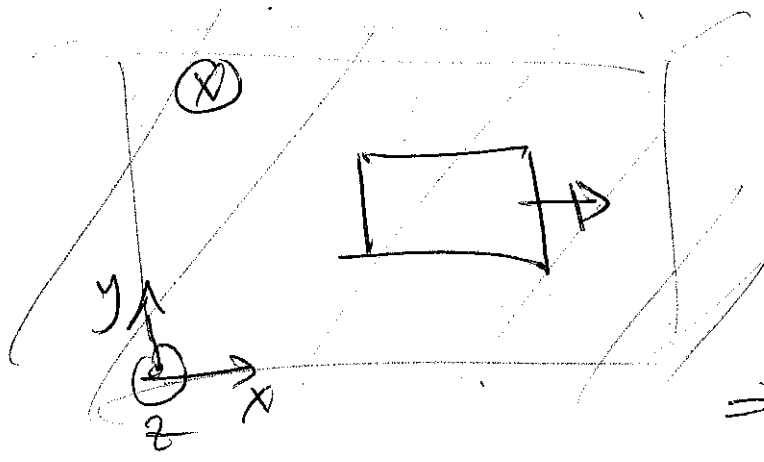
Ex. 2



Flux increases, EMF will be created

Ex. 3

$$\mathbf{B} = -(\lambda x) \hat{k}$$



Flux changes
 because \vec{B} -field
 is not uniform
 \Rightarrow EMF created.

MORE EXAMPLES LATER

* Faraday's law

$$\Sigma = - \frac{d\Phi_B}{dt} = - \frac{d}{dt} \int \vec{B} \cdot d\vec{S}$$

\rightarrow Found experimentally by Faraday (reported 1831)

\rightarrow Can be derived using ^{the} Lorentz force law.

\rightarrow Leads to Maxwell's third equation:

$$\Sigma = \oint \vec{E} \cdot d\vec{l} = \int (\nabla \times \vec{E}) \cdot d\vec{S} \quad (\text{Stokes theorem})$$

$$- \frac{d}{dt} \int \vec{B} \cdot d\vec{S} = \int \left(- \frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{S}$$

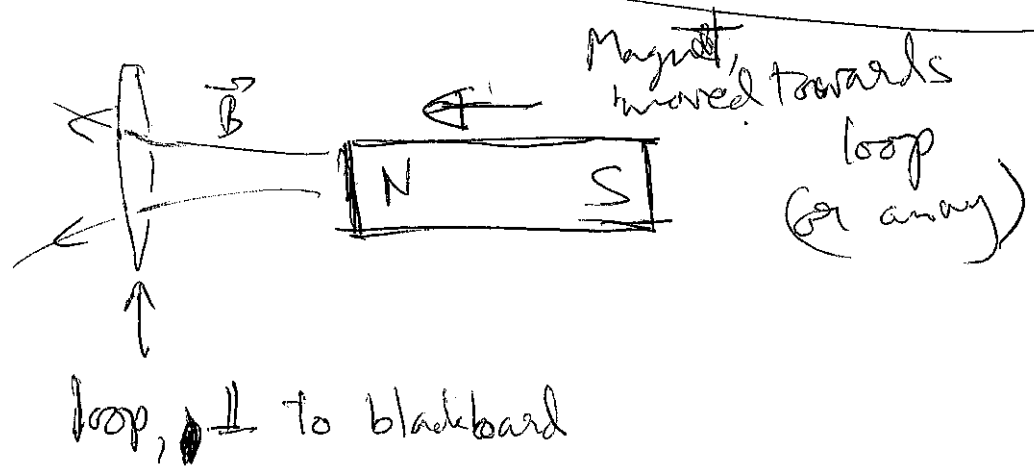
Thus $\int (\nabla \times \vec{E}) \cdot d\vec{S} = \int \left(- \frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{S} \Rightarrow \boxed{\nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t}}$

Faraday's

MAXWELL'S EQNS COMPLETED

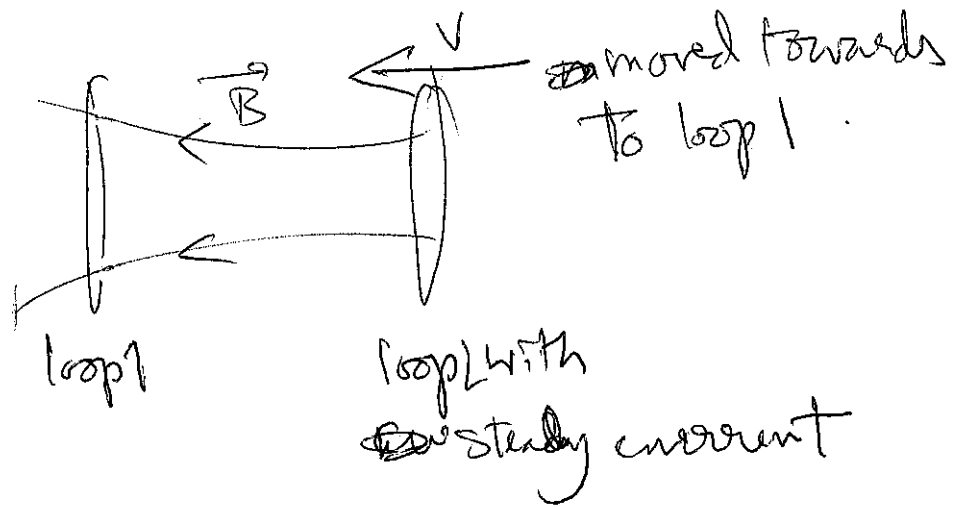
EXAMPLES, INDUCTION, CONTD

Ex. 4

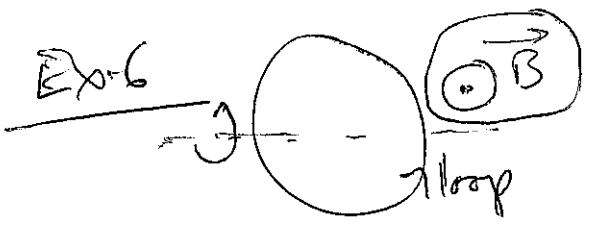


Flux changes \Rightarrow EMF created.

Ex. 5



Magn. flux thru loop 1 changes \Rightarrow EMF created



Rotating loop \Rightarrow flux changes. If rotation constant, $\Phi_B = BA \cos \omega t$

$\Rightarrow \mathcal{E} = BA \omega \sin \omega t$

* FARADAY'S LAW IN INTEGRAL FORM

$$\oint_C \vec{E} \cdot d\vec{l} = - \frac{d}{dt} \int_{\Sigma} \vec{B} \cdot d\vec{S} = - \int_{\Sigma} \left(\frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{S}$$

Where the curve C encloses the surface Σ .

⇒ Comparison with Ampere's law for magnetic fields? (static)

$$\oint_C \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enc}} = \int_{\Sigma} (\mu_0 \vec{J}) \cdot d\vec{S}$$

Piercing / Enclosed current causes "curly" magn-field

$$\oint_C \vec{E} \cdot d\vec{l} = - \int_{\Sigma} \left(- \frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{S}$$

Enclosed / piercing time-dependent magnetic field causes "curly" electric field.

* TWO TYPES OF ELECTRIC FIELDS

$$\text{EMF } \mathcal{E} = \oint_C \vec{E} \cdot d\vec{l}$$

Q. Why didn't we just say voltage = "potential difference"

5C

A: Because potential is not defined.

⇒ Definition $\vec{E} = -\vec{\nabla}V$ requires $\vec{\nabla} \times \vec{E} = 0$

Now we have $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$;

(studying physics beyond electrostatics.)

In electrostatics, $\oint \vec{E} \cdot d\vec{l} = 0$, because



$$\oint \vec{E} \cdot d\vec{l} = V_A - V_A = 0$$

(potential difference of a point with itself.)

2 TYPES of \vec{E} fields

Electric

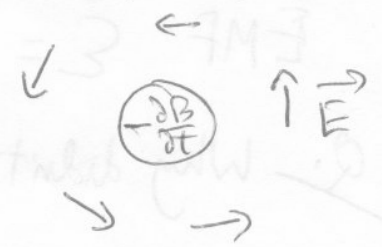
Fields created in electrostatics :

- field lines end or start at charges.
- zero curl.



Electric fields created by induction (changing \vec{B}) :

- field lines loop around onto themselves
- no divergence.



* Maxwell's 4 equations

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}, \quad \nabla \cdot \vec{B} = 0$$

$$\nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \quad \text{electromagnetic induction}$$

$$\nabla \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

* We derived the term

$$\mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t} = \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

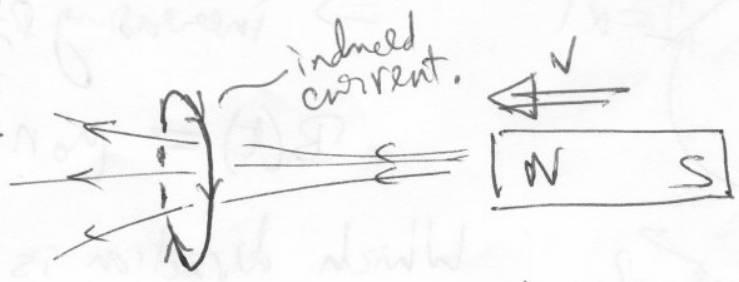
by imposing the continuity equation. This quantity is called the **DISPLACEMENT CURRENT**

* LENZ'S LAW (fixes the direction of induced EMF/current)

Currents induced by change in magnetic flux ~~oppose the change, through the B-field created by the induced current.~~

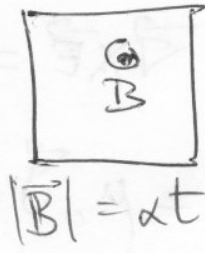
oppose the change, through the \vec{B} -field created by the induced current.

Example 1:



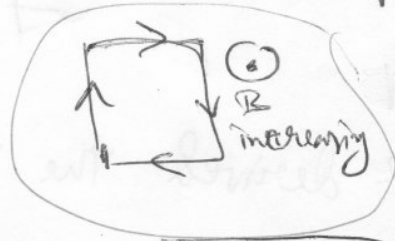
Flux increasing. Induced current will **OPPOSE** increase.
 \Rightarrow Will point rightward.

Example 2a



increasing $|\vec{B}|$

induced current opposes increase



induced field points INWARD

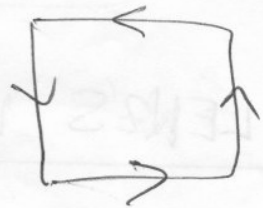
Example 2b



decreasing $|\vec{B}|$, e.g. $|\vec{B}| \propto B_0 e^{-\alpha t}$

induced current opposes decrease

\Rightarrow ~~induced field~~ field due to induced current points UP.

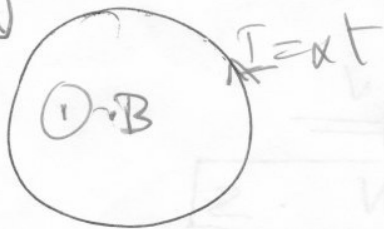


Example 3

(Without ~~wire~~ a circuit/wire!)

Changing current in Solenoid

CROSS-SECTION OF SOLENOID



Increasing solenoid current \Rightarrow increasing \vec{B} -field / flux

$B(t) = \mu_0 n I(t) = \mu_0 n \alpha t$

? \vec{E} ?

Which direction is the induced \vec{E} -field?

$\oint \vec{E} \cdot d\vec{l} = \int \left(-\frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{A}$

Answer! imagine a wire loop circling around solenoid. Induced EMF should OPPOSE INCREASE of flux \Rightarrow imagined induced current should create \vec{B} -field downward.
 \Rightarrow induced \vec{E} -field points CLOCKWISE, opposite direction of increasing current in solenoid.

* Lenz's law corresponds to a ^{negative} SIGN in Faraday's law.

\rightarrow Lenz's law makes sense energetically, because other sign would lead to perpetual energy production.

* EXERCISE!



Loop is being deformed so that loop area DECREASES. \vec{B} is constant, and \perp to plane.

Find the ~~area~~ ^{direction} of the induced current.